

Towards An Operational (La)T_EX Package Supporting Optical Scaling of Dynamic Mathematical Symbols

Abdelouahad BAYAR
a.bayar@uca.ma

Cadi Ayyad University
École Supérieure de Technologie de Safi
(High College of Technology)

July 27, 2016

- Handling of dynamic mathematical symbols is still a hard problem
- (Some)T_EX and PostScript Type 3 to supply a solution
- A T_EX (luaT_EX) package supporting optical scaling and supplying the habitual way to format scientific documents

- 1 Mathematical formula: State and Problems
- 2 The Requirements to handle dynamic mathematical symbols taking care of optical scaling
- 3 The Design of the system
- 4 Implementation

- Static mathematical symbols
- Variable sized symbols (Dynamic mathematical symbols)

- Linear scaling

$$\left\{ \begin{array}{l} a_{11}x_1 + \dots \\ a_{21}x_1 + \dots \end{array} \right\} \left\{ \begin{array}{l} a_{11}x_1 + \dots \\ a_{21}x_1 + \dots \\ a_{31}x_1 + \dots \end{array} \right\} \left\{ \begin{array}{l} a_{11}x_1 + \dots \\ a_{21}x_1 + \dots \\ a_{31}x_1 + \dots \\ a_{41}x_1 + \dots \end{array} \right\}$$

- Linear scaling

$$\left\{ \begin{array}{l} a_{11}x_1 + \dots \\ a_{21}x_1 + \dots \end{array} \right\} \left\{ \begin{array}{l} a_{11}x_1 + \dots \\ a_{21}x_1 + \dots \\ a_{31}x_1 + \dots \end{array} \right\} \left\{ \begin{array}{l} a_{11}x_1 + \dots \\ a_{21}x_1 + \dots \\ a_{31}x_1 + \dots \\ a_{41}x_1 + \dots \end{array} \right\}$$

- Optical scaling

$$\left\{ \begin{array}{l} a_{11}x_1 + \dots \\ a_{21}x_1 + \dots \end{array} \right\} \left\{ \begin{array}{l} a_{11}x_1 + \dots \\ a_{21}x_1 + \dots \\ a_{31}x_1 + \dots \end{array} \right\} \left\{ \begin{array}{l} a_{11}x_1 + \dots \\ a_{21}x_1 + \dots \\ a_{31}x_1 + \dots \\ a_{41}x_1 + \dots \end{array} \right\}$$

- Metal typesetting

$$(1) \left\{ \begin{array}{c} ds \\ ds_1 \\ ds_2 \end{array} \right\} \begin{array}{|c|c|c|} \hline & \rho & \rho_1 & \rho_2 \\ \hline & A & \mathcal{E}_2 & \mathcal{E}_1 \\ \hline & \mathcal{E}_2 & A_1 & \mathcal{E} \\ \hline & \mathcal{E}_1 & \mathcal{E} & A_2 \\ \hline & \varpi & \varpi_1 & \varpi_2 \\ \hline \end{array}$$

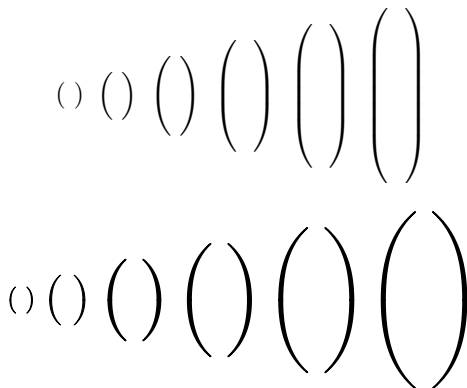
- Digital typesetting

- math-fly/Grif
- Curext
- T_EX/L^AT_EX
 - Support of mathematical formulas with multiple variable-sized symbols

$$\left(\begin{array}{cc} \begin{pmatrix} a & b \\ c & d \end{pmatrix} & \begin{pmatrix} e & f \\ g & h \end{pmatrix} \\ 0 & \begin{pmatrix} i & j \\ k & l \end{pmatrix} \end{array} \right)$$

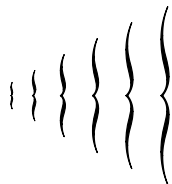
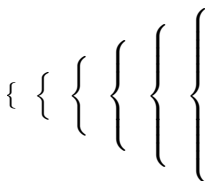
- T_EX/L_AT_EX

- The thickness remains constant after some level
- Some symbols differ from corresponding ones in metal typesetting with regard to the shape after a level of size



- T_EX/L_AT_EX

- Some symbols differ from their corresponding in metal typesetting with regard to the shape at all sizes.



- Font requirements
- Document processing system requirements
- use Requirements by end-users
- Required Font for (La)\T_EX: PostScript Type 3

dynMath.tex

⋮

`\special{!``: some useful PostScript procedures``/w 0 def``/h 0 def``/fs 0 def``/dynMathFont 8 dict def``dynMathFont begin``/FontType 3 def``/FontMatrix [0.001 0 0 0.001 0 0] def``/FontBBox [0 0 1000 1000] def``/Encoding 256 array def``0 1 255 {Encoding exch /.notdef put} for`

dynMath.tex

```

Encoding 0 /leftPar put % Left parenthesis = 0
Encoding 1 /rightPar put % Right parenthesis = 1
Encoding 8 /leftBrace put % Left brace = 8
Encoding 9 /rightBrace put % Right brace = 9
:
:
:/Charprocs - individual glyph descriptions
:
:
:/BuildGlyph definition
:
:
:/BuildChar defintion
:

```

dynMath.tex

```
currentdict
end % End of font dictionary
/dynMath exch definefont pop%
}
:
: Some useful TeX defintions
:
% #1:left delimiter, #2:formula, #3:right delimiter
\def\meLeft#1#2\meRight#3{
: macro defintion
}
```

\backslash meLeft macro

The macro \backslash meLeft has to :

- 1 Compute the dimensions of the formula (in the correct math style): \backslash hf, \backslash df and \backslash wf
- 2 Determine vertical and horizontal stretching amounts: \backslash h and \backslash w
- 3 Calculate the size of the font \backslash fs in which dynMath will be used
- 4 Determine the dimensions of the left symbol: \backslash symHeight, \backslash symWidth and \backslash symDepth

\meLeft macro

- 5 Build an horizontal box \efbDel:

```
\setbox\efbDel\hbox {
  \special{" ...
  /fs ... store
  /h ... store
  /w ... store
  /dynMath findfont fs scalefont setfont
  <code of The left symbol> show
}
```

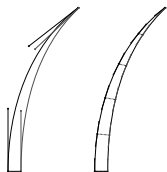
- 6 Set the dimensions of \efbDel to \symHeight, \symWidth and \symDepth
- 7 Write the content of \efbDel

\meLeft macro

- 8 Write the mathematical formula
- 9 Apply steps from the second to the seventh to deal with the right delimiter

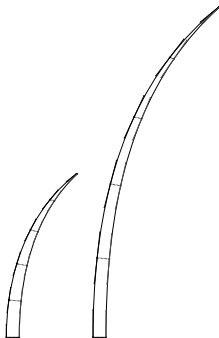
- └ The Design of the system
- └ Design of dynMath font

Symbol parametrizing stretching - Concepts



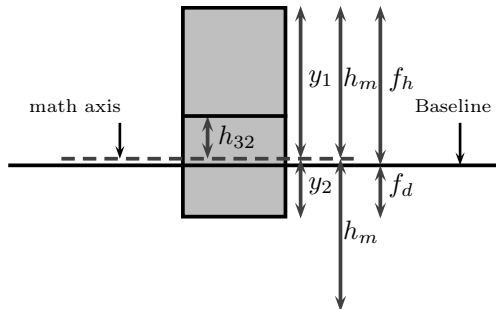
- └ The Design of the system
- └ Design of dynMath font

Symbol parametrizing stretching - Concepts



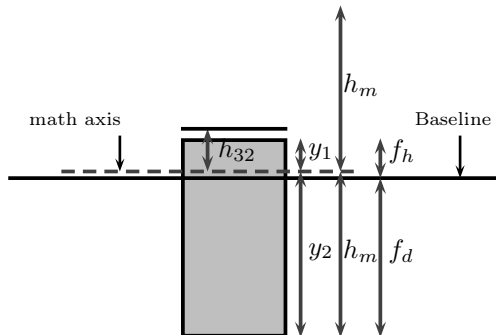
Mathematical formula characteristics

- High mathematical formula



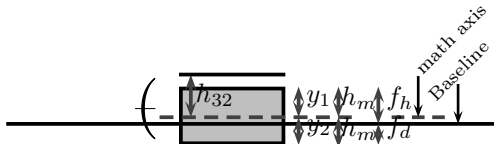
Mathematical formula characteristics

- Deep mathematical formula



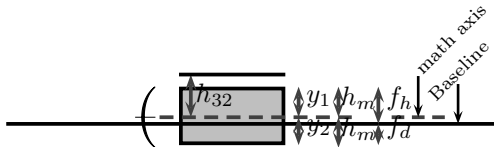
Scaling - $h_m \leq h_{32}$

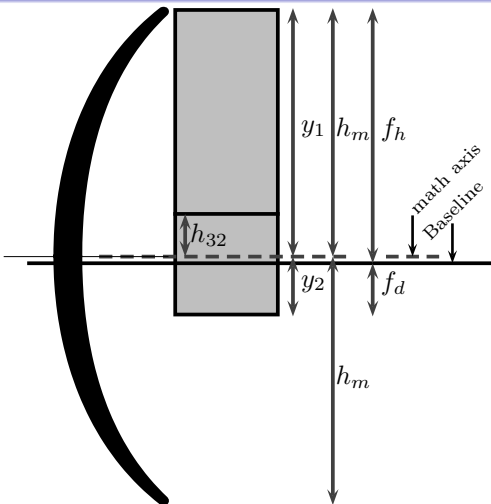
$$f_s = \frac{1003.75 \times h_m}{h_{1000}}$$

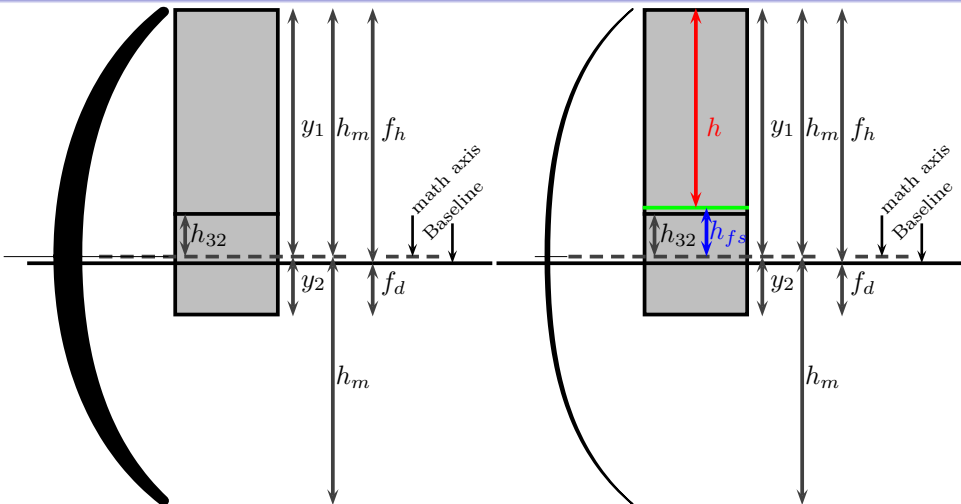


Scaling - $h_m \leq h_{32}$

$$f_s = \frac{1003.75 \times h_m}{h_{1000}}$$



Scaling - $h_m > h_{32}$ 

Scaling - $h_m > h_{32}$ 

Scaling - $h_m > h_{32}$

$$h_{max}^p = \frac{32700 \times 32}{1000} = 1190.4$$

Scaling - $h_m > h_{32}$

$$h_{max}^p = \frac{32700 \times 32}{1000} = 1190.4$$

$$h_{max} = 1.00375 \times h_{max}^p \text{pt}$$

Scaling - $h_m > h_{32}$

$$h_{max}^p = \frac{32700 \times 32}{1000} = 1190.4$$

$$h_{max} = 1.00375 \times h_{max}^p \text{pt}$$

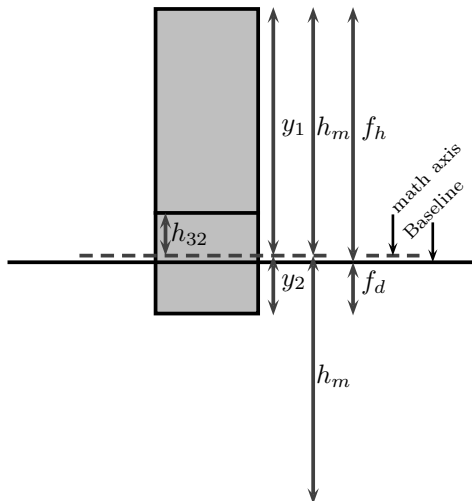
$$h_{max} = 1194.864 \text{pt}$$

Scaling - $h_m > h_{32}$

$$e(h_m) = c_1 h_m + c_0$$

such that:

- $e(h_{32}) = e_{32}$
- $e(h_{max}) = \lambda e_{32}$
- e_{32} : thickness of the dynamic symbol in body 32
- λ : a scaling factor (3.236)

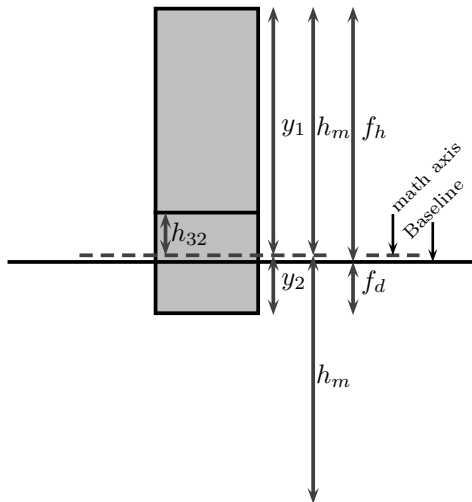


Scaling - $h_m > h_{32}$

$$f_s = \frac{1003.75}{e_{1000}} e$$

Scaling - $h_m > h_{32}$

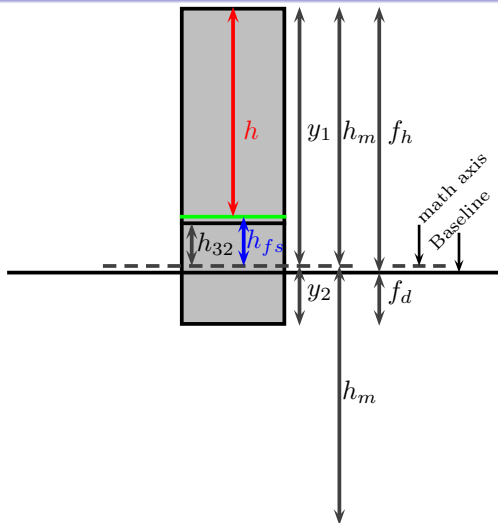
$$fs = \frac{1003.75}{e_{1000}} e$$



Scaling - $h_m > h_{32}$

$$f_s = \frac{1003.75}{e_{1000}} e$$

$$h_{f_s} = \frac{h_{1000}}{1003.75} f_s$$



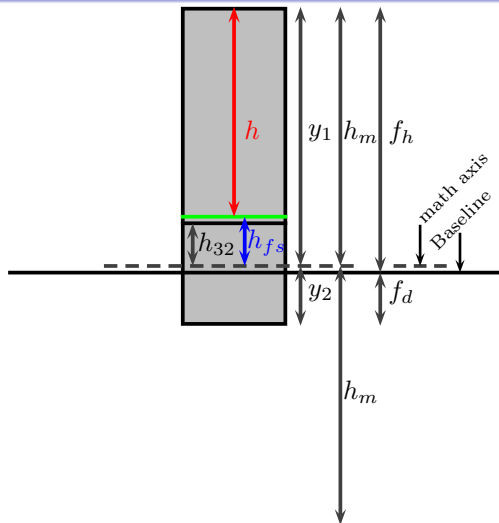
Scaling - $h_m > h_{32}$

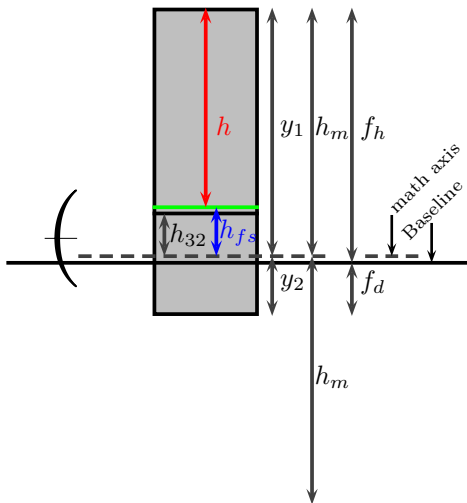
$$fs = \frac{1003.75}{e_{1000}} e$$

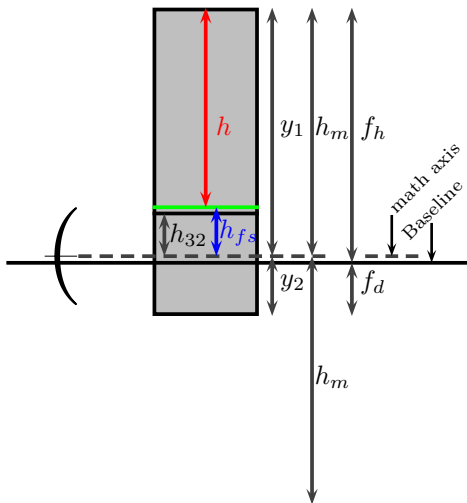
$$h_{fs} = \frac{h_{1000}}{1003.75} fs$$

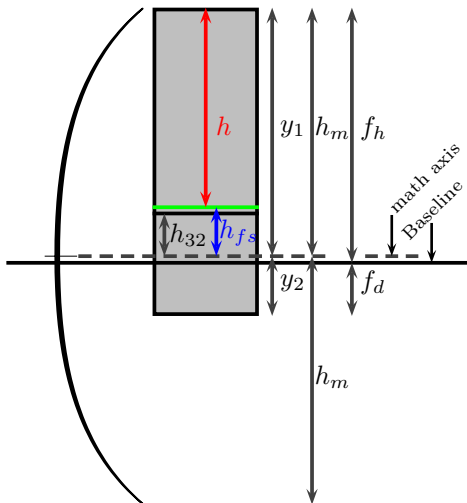
$$h = h_m - h_{fs}$$

$$w = \text{function}(h)$$



Scaling - $h_m > h_{32}$ 

Scaling - $h_m > h_{32}$ 

Scaling - $h_m > h_{32}$ 

- dynMath: Simple T_EX source File
- dynMath: Mini-package
- dynMath for all(T_EX): limited and slow
- dynMath for LuaT_EX (dvluaT_EX and dvlua^AT_EX): good

- Conclusions:
 - Support of dynamic mathematical symbols with respect to Optical Scaling is feasible.
 - The feasibility is proved with Parentheses and Braces which are adequate representing samples.
- Perspectives:
 - Support of all dynamic mathematical symbols
 - Improvement of quality of symbols (Study of optical scaling considering the artistic viewpoint)